

The luminosity function of the hot and cold Kuiper belt populations

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ABSTRACT

We have performed an ecliptic survey of the Kuiper belt, with an areal coverage of 8.9 square degrees to a 50% limiting magnitude of $r'_{ Sloan} = 24.7$, and have detected 88 Kuiper belt objects, roughly half of which received follow-up 1–2 months after detection. Using this survey data alone, we have measured the luminosity function of the Kuiper belt, thus avoiding any biases that might come from the inclusion of other observations. We have found that the *Cold* population defined as having inclinations less than 5° has a luminosity function slope $\alpha_{Cold} = 0.82 \pm 0.23$, and is different from the *Hot* population, which has inclinations greater than 5° and a luminosity function slope $\alpha_{Hot} = 0.35 \pm 0.21$. As well, we have found that those objects closer than 38 AU have virtually the same luminosity function slope as the *Hot* population. This result, along with similar findings of past surveys demonstrates that the dynamically *Cold* Kuiper belt objects likely have a steep size distribution, and are unique from all of the excited populations which have much shallower distributions. This suggests that the dynamically excited population underwent a different accretion history and achieved a more evolved state of accretion than the *Cold* population. As well, we discuss the similarities of the *Cold* and *Hot* populations with the size distributions of other planetesimal populations. We find that while the Jupiter family comets and the scattered disk exhibit similar size distributions, a power-law extrapolation to small sizes for the scattered disk cannot account for the observed influx of comets. As well, we have found that the Jupiter Trojan and *Hot* populations cannot have originated from the same parent population, a result that is difficult to reconcile with scattering models similar to the NICE model. We conclude that the similarity between the size distributions of the *Cold* population and the Jupiter Trojan population is a striking coincidence.

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1. Introduction

The size distribution is one of the most fundamental properties of a planetesimal population. As the size of an object is primarily determined from its accretion and collisional disruption histories, the size distribution can reveal important information on the accretion and collisional history of that population (for a recent example, see Bottke et al., 2005).

Unlike the closer populations such as the asteroid belt, whose proximity has allowed the accurate measurement of their size distributions (see for example Jedicke and Metcalfe, 1998; Jewitt et al., 2000), the distance to the Kuiper belt has prevented an equally detailed determination of its size distribution. Observations thus far have demonstrated that for the Kuiper belt as a whole, the size distribution for objects with diameters, $D \gtrsim 200$ km, is well described by a power-law. At some size $50 \lesssim D \lesssim 150$ km, the size distribution rolls-over to a shallower distribution (Bernstein et al., 2004; Fuentes et al., 2009; Fraser and Kavelaars, 2009). Smaller than the roll-over, the size distribu-

tion appears to remain shallow to objects as small as $D \sim 1$ km (Schlichting et al., 2009; Bianco et al., 2010).

While the accuracy of current measurements prevents a detailed modeling of the history of objects in the region, some insight has already been gained. The steepness of the large object size distribution implies that for this population, accretion was a short-lived phenomenon, likely not more than a few 100 Myr (Gladman et al., 2001; Kenyon, 2002; Fraser et al., 2008). The paucity of the observed belt, and the existence of the largest known members demonstrates that the belt has undergone significant mass depletion, losing as much or more than 99% of its primordial mass (Stern and Colwell, 1997; Kenyon and Luu, 1998; Jewitt and Sheppard, 2002; Fuentes et al., 2009). The existence of the roll-over at sizes larger than $D \gtrsim 50$ km suggests that the belt has undergone significant collisional comminution in a region of significantly increased density compared to today (Kenyon and Bromley, 2004; Benavidez and Campo Bagatin, 2009; Fraser, 2009).

As well, recent observations have suggested that the size distribution of those dynamically *Cold* (low inclinations and eccentricities) Kuiper belt objects is different than that of the dynamically *Hot* (large inclinations and eccentricities) population (Levison and Stern, 2001). Bernstein et al. (2004) found that the size distri-

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bution of objects with inclinations, $i < 5^\circ$ was steeper than the size distribution of objects with $i > 5^\circ$. Fuentes and Holman (2008) found similar results showing that the *Cold* population had a steeper slope than the mixed populations as a whole. This result implies that the *Hot* and *Cold* populations are genetically separate populations, that have significantly different accretion and evolution histories.

The results of Bernstein et al. (2004) were drawn from samples of objects compiled from many different surveys. This practice was necessitated by available data. All surveys had either shallow limiting magnitudes and a large areal coverage, or vice-versa. The result was that most surveys did not have a sufficient range of objects for which the size distribution could be accurately measured from that survey alone. The practice of using data from multiple surveys opens the results to the possibility of being affected by calibration issues and variations in sky density which could lead to an incorrect measurement of the size distribution. When these effects were properly accounted for, Fraser et al. (2008); Fraser and Kavelaars (2009) found that these data could not be used to reliably test differences in subpopulations of the Kuiper belt.

Here we present the results of a new Kuiper belt survey. By virtue of the survey's design, a large number of objects were discovered and followed to determine their inclinations, over a range of sizes sufficient to measure the size distribution for the *Hot* and *Cold* population without the use of other surveys. In Section 2 we present our observations, and our data reductions and discovery techniques. In Section 3 we present the analysis of our results, in Section 4 we discuss the implications of our results, and we end with concluding remarks in Section 5.

2. Observations and reductions

2.1. Discovery observations

The discovery observations were made on October 18, 2009 (UT) with Suprime-cam on the 8.2 m Subaru telescope (Miyazaki et al., 2002). Suprime-cam is 10-chip mosaic camera, with a field-of-view of roughly $34' \times 27'$ with $\sim 15''$ chip-gaps, and has a pixel scale of $0.2''$. The observations consisted of imaging 34 fields, each visited three times in the r' filter with the camera long axis oriented horizontally in RA, with each visit consisting of a single 200 s exposure. The first and last images of a field were separated by roughly 6.5 h. The observed fields were all within $\sim 1.5^\circ$ of the ecliptic and within $\sim 10^\circ$ of opposition at the discovery epoch. The total areal coverage of our survey after accounting for chip-gaps was 8.93 square degrees. Details of the individual fields are shown in Table 1 and Fig. 1. The observations included multiple images of the D1 and D4 fields of the Canada–France–Hawaii Telescope Supernova Legacy Survey (Astier et al., 2006) at various airmasses to provide both photometric and astrometric calibrations of the discovery images.

The images were pre-processed with standard techniques; the bias levels were removed, and a master bias frame, set as the average of 10 bias images was removed from all science frames. A master sky-flat was produced from the science frames using a clipped median filter, and was removed from the science images producing background variations no larger than $\sim 1\%$ across a mosaic.

Photometric calibrations were done on a chip-by-chip basis using the Mega-pipe source catalog of the D1 and D4 fields (Gwyn, 2008). The zeropoint was found to be identical for all chips within uncertainties, with a value, $Z_{r_{\text{Subaru}}} = 27.50 \pm 0.02$. The conversion from the Suprime-cam instrumental magnitudes to those of Mega-pipe was found to be

$$m(r')_{\text{Suprime}} = m(r')_{\text{Mega}} - 0.018(g'_{\text{Mega}} - r'_{\text{Mega}}) \quad (1)$$

Table 1

Suprime-cam discovery field centers. Coordinates are presented in the J2000 epoch.

Right ascension	Declination
01:45:59.0	+10:03:00.0
01:46:29.7	+11:24:00.0
01:48:27.6	+10:30:00.0
01:48:59.1	+11:51:00.0
01:50:46.1	+10:30:00.0
01:51:07.5	+11:24:00.0
01:51:29.0	+12:18:00.0
01:51:39.8	+12:45:00.0
01:52:53.7	+10:03:00.0
01:53:15.5	+10:57:00.0
01:53:37.3	+11:51:00.0
01:53:48.3	+12:18:00.0
01:54:10.4	+13:12:00.0
01:55:34.1	+10:57:00.0
01:55:45.3	+11:24:00.0
01:56:30.2	+13:12:00.0
01:58:15.6	+11:51:00.0
01:58:50.0	+13:12:00.0
02:00:34.7	+11:51:00.0
02:07:32.1	+11:51:00.0
02:07:44.5	+12:18:00.0
02:07:56.8	+12:45:00.0
02:08:09.3	+13:12:00.0
02:09:51.3	+11:51:00.0
02:10:16.4	+12:45:00.0
02:12:23.2	+12:18:00.0
02:13:01.8	+13:39:00.0
02:15:08.7	+13:12:00.0
02:15:21.8	+13:39:00.0
02:17:15.2	+12:45:00.0
02:17:28.5	+13:12:00.0
02:21:54.3	+12:45:00.0
02:22:21.9	+13:39:00.0
02:22:35.8	+14:06:00.0
02:24:13.9	+12:45:00.0

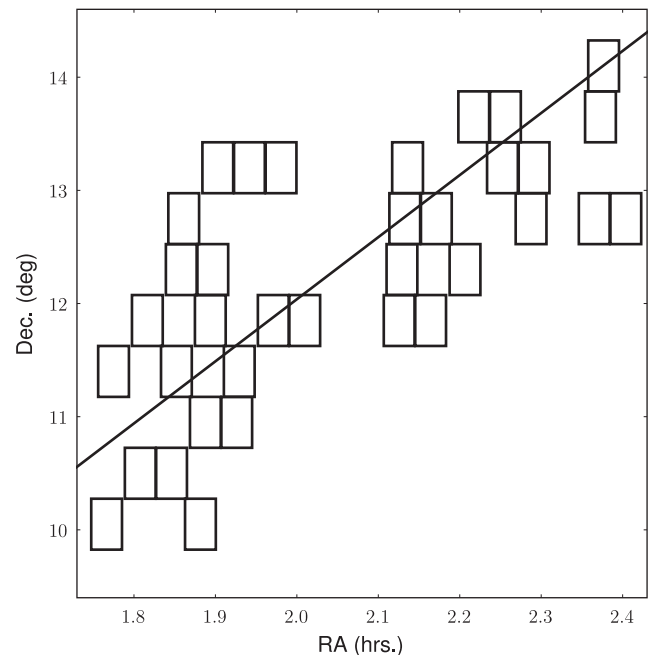


Fig. 1. Diagram of the fields observed for moving objects during the Subaru observations. These fields were chosen to avoid bright stars. The field center coordinates are presented in Table 1.

Atmospheric extinction was measured from the science frames. The airmass correction was found to be 0.08 magnitudes per unit

increase in airmass. Comparison of common background sources in each triplet revealed no large seeing or transparency variations throughout the night (see Figs. 2 and 3); the night was photometric.

The Suprime-cam field of view is highly distorted, especially near field edges, requiring calibration to ensure accurate astrometry of moving sources in the observations. *Scamp* (Bertin, 2006) was used to measure second order spatial distortions of the Suprime-cam field, from the D1 and D4 fields on a chip-by-chip basis. Little variance in the distortions was found over the airmass range of these observations. Thus, a master distortion map for each chip was produced from all images of the D1 and D4 fields. Absolute calibration of each science image was done using the USNO-B catalog, and the master distortion map, resulting in residuals of roughly $0.3''$. Relative astrometry between the three images of each field – a triplet – was performed by matching sources between an image, and the reference image, chosen as the image of the triplet with the lowest absolute residuals. This resulted in an excellent common astrometric solution for the triplet, with residuals of $\lesssim 0.06''$ between all three images. This calibration procedure ensured reliable astrometry to both maximize the discovery efficiency of moving sources, as well as secure the possibility of follow-up on future dates.

2.2. Moving object search

The Suprime-cam data were utilized to search for moving objects in the Solar System, in and beyond the orbits of the gas-giant planets. To characterize the detection efficiency of our moving object detection method, artificial moving point sources were implanted in the observations.

The stellar point-spread function (PSF) was generated on an image-by-image and chip-by-chip basis from 10 to 15 hand-selected, visually inspected point sources for each chip. It was found that a spatially constant PSF was sufficient to model the stellar shape across a chip. The PSFs were created using the tools in the *doaphot* package of *IRAF* and for each image consisted of an average Moffat profile with look-up table of the PSF stars of that chip.

Random artificial sources were generated on Sun-bound orbits, with semi-major axes, $18 \leq a \leq 1000$ AU, eccentricities, $e \leq 0.6$, and inclinations, $i \leq 90^\circ$. Anomaly, periaipse, and nodal angles were chosen at random to ensure that the sources fell in the images and

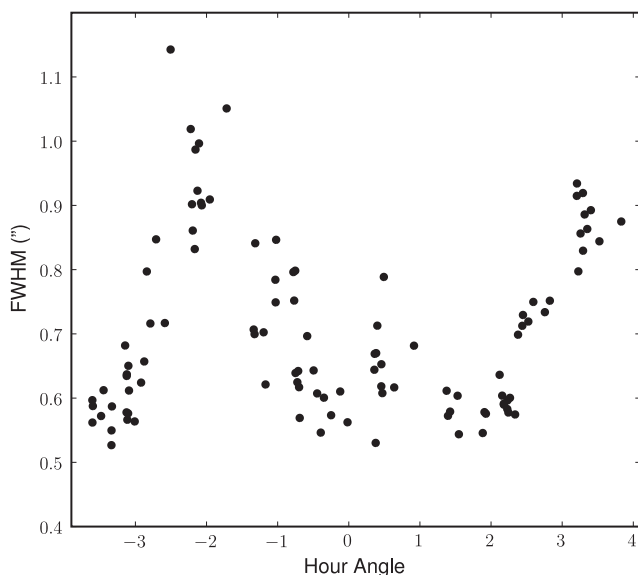


Fig. 2. Point source full-width at half maximum versus hour angle of all Subaru discovery observations.

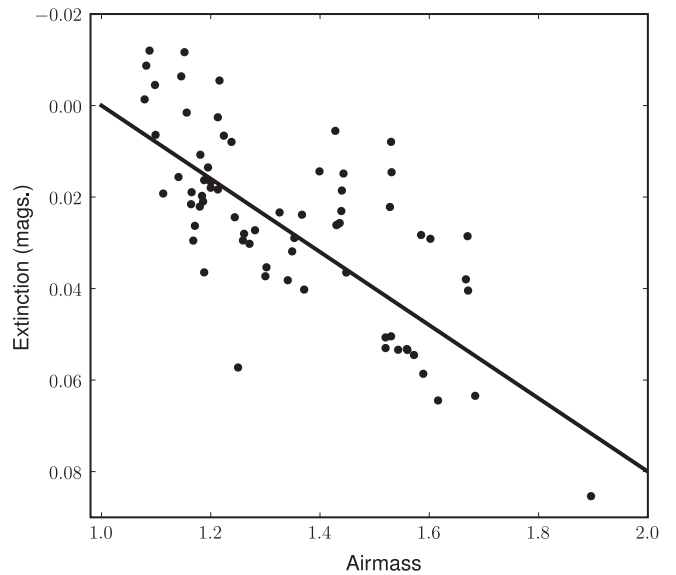


Fig. 3. Extinction versus airmass for the Subaru discovery observations. Each point is the average difference in magnitude of bright stars between common fields; each of the 35 discovery triplets has two data points. The line is the best-fit linear extinction law, with slope 0.08 magnitudes per unit airmass. These data demonstrate the photometric nature of the discovery observations.

could be either approaching or receding from their nodes. Twenty to thirty artificial sources were planted in each chip with apparent magnitudes in the range $21 \leq r' \leq 26.5$ with image-to-image flux variations matching those measured from 30 to 40 bright stars common to each image of a triplet, thus ensuring that any extinction variations throughout the observations were accounted for. If an artificial source's motion would cause it to drift more than 0.2 pixels during an exposure, it was broken up into multiple fainter sources with 0.2 pixel spacing and a total flux equal to that of the artificial source. Thus, trailing effects were fully accounted for in our search.

Moving objects were identified by their motions between images of a triplet. Using *SExtractor* (Bertin et al., 2002), all sources in an image were tabulated. Stationary sources common to each image in a triplet were flagged, and ignored from further consideration, leaving only those sources who were either moving, or had highly variable fluxes. The remaining sources of an image triplet were then searched for motion consistent with Sun-bound objects. Candidate sources were chosen as any three individual point-source detections, one per image, whose centroid moved at least one pixel ($0.2''$) and at most $\sim 5''$ between each image. These candidate sources were then further filtered by *fit_radec* (Bernstein and Khushalani, 2000). If the best-fit orbit to the candidate had a chi-squared larger than 7.5, the candidate was rejected. The results of this were approximately 16,000 candidate sources which were then visual inspected by an operator for final acceptance or rejection.

The majority of visually inspected candidates were false, primarily caused by cosmic ray impacts, or extended sources which were identified by *SExtractor* as more than one source in some images. Of the 16,000 candidates, roughly a third were matched with implanted artificial sources. From these sources, the performance of the search routine was characterized. The results are shown in Fig. 4. As can be seen, the detection efficiency is well described by the familiar functional form

$$\eta(r') = \frac{A}{2} \left(1 - \tanh \left(\frac{r' - m_*}{g} \right) \right) \quad (2)$$

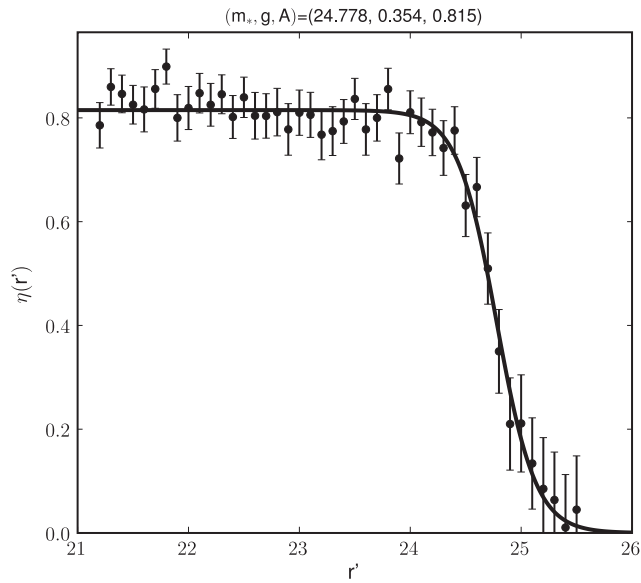


Fig. 4. Detection efficiency versus artificial source r'_{Subaru} magnitude. Error-bars are 1-sigma poisson limits. Best-fit parameters of the efficiency function given by Eq. (2) are presented at the top of the figure.

where A , m^* , and g are the maximum efficiency, half-maximum magnitude, and half-width parameters. The survey achieved a 50% limiting magnitude for discovery of $r' = 24.7$. The search was found to be sensitive to objects as distant as ~ 900 AU, beyond which, insufficient motion was exhibited for reliable detection. No significant variation in search efficiency with inclination or eccentricity was found (see Figs. 5 and 6).

The search resulted in the detection of 88 sources. The sources' distances and inclinations were determined with *fit_radec*. Photometry was measured using standard aperture photometry techniques with corrections for airmass applied (see Fig. 3). Aperture corrections were measured from the bright stars from which the PSFs were generated. Photometric uncertainties were determined from the function

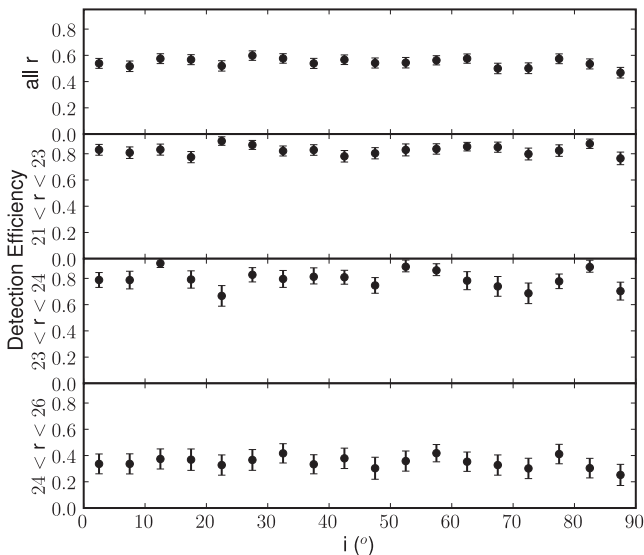


Fig. 5. Detection efficiency versus artificial object inclination. From top to bottom, all planted sources, and those with $r' < 23$, $23 < r' < 24$, $24 < r' < 26$. This figure demonstrates that, given a particular object magnitude, our survey was equally sensitive to all inclinations.

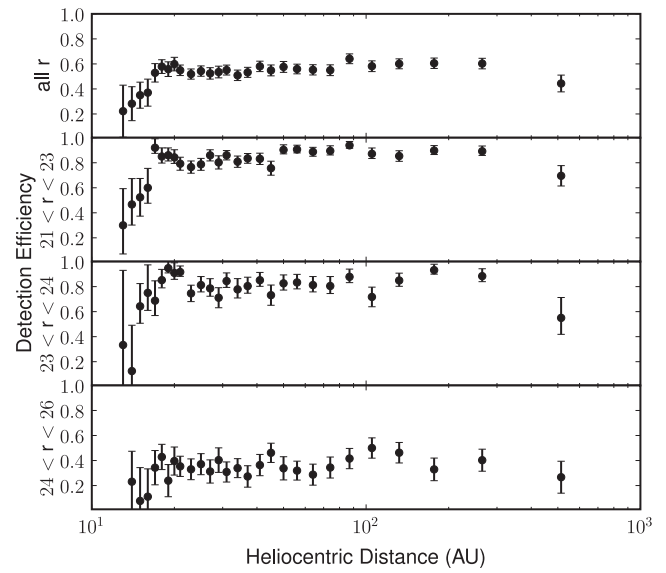


Fig. 6. Detection efficiency versus artificial object heliocentric distance. From top to bottom, all planted sources, and those with $r' < 23$, $23 < r' < 24$, $24 < r' < 26$. This figure demonstrates that, given a particular object magnitude, no significant variation of detection efficiency with distance is apparent. Exceptions are at the extrema of the survey; our search was only sensitive to objects with apparent motions $0.2\text{--}10''/\text{h}$ roughly corresponding to distances $15 \leq r \leq 800$ AU.

$$\Delta r' = \delta + \gamma 10^{\frac{r'-Z}{2.5}} \quad (3)$$

where δ is a constant representing the extinction stability of the night in question, γ is a constant proportional to the parameters of the detector (see Fraser et al., 2008 for a derivation), and Z is the telescope photometric zeropoint. This function was fit to the difference in measured and planted magnitudes of the artificial sources. The best-fit parameters are $(\delta, \gamma) = (0.028, 3.25)$. The best-fit δ is in agreement with the scatter in extinction exhibited in Fig. 3. Along with the measured fluxes with uncertainties sampled per measurement from Eq. (3), these results are presented in Table 2.

One detected object was identified as previously known Plutino 2004 VT75 which was not known to be in the observed fields prior to detection. This detection confirmed the accuracy of both the photometric and astrometric calibrations. The detected position of 2004 VT75 was $\sim 0.2''$ from that predicted from the Minor Planet Center. As well, this source was detected across different chips demonstrating that the astrometric fits for different chips of the same mosaic image are reliable in an absolute sense.

2.3. Follow-up

For a subset of the objects, follow-up observations were performed with the Low Resolution Imaging Spectrometer (LRIS) on the Keck-I telescope on the nights of November 21st, 22nd and December 21st, 2009 (UT). LRIS is a dual channel (blue and red) camera, with each camera, a 2 CCD mosaic having approximately a $6 \times 8'$ field of view, with a $\sim 25''$ gap, and a pixel scale of $0.135''$. This particular instrument is convenient for our follow-up observations, as the positional uncertainty ellipse of our targets at the time of follow-up was slightly smaller than the areal coverage of a single detector CCD.

The follow-up observations consisted of pairs of images at the positions of each target, predicted from *fit_radec*, with temporal spacing between each image sufficient to detect the object's motion. By virtue of the dual channel imaging abilities of the camera, images in both the g and r LRIS filters were taken simultaneously.

Table 2
Discovery Subaru magnitudes and Sloan magnitudes.

Object ^a	r'_{Subaru}	r'_{SDSS}	$(g_{\text{SDSS}} - r'_{\text{SDSS}})$	R^b (AU)	i^b (deg.)
obj_0	25.2 ± 0.1	25.0 ± 0.1	–	42.0 ± 3.0	10.0 ± 9.0
obj_1	24.55 ± 0.07	24.52 ± 0.07	–	42.0 ± 3.0	2.0 ± 8.0
obj_2	24.75 ± 0.08	24.72 ± 0.08	–	40.0 ± 3.0	20.0 ± 10.0
Nobj_3	23.99 ± 0.05	24.02 ± 0.05	0.46 ± 0.09	41.0 ± 3.0	4.0 ± 2.0
obj_4	24.71 ± 0.08	24.65 ± 0.08	–	43.0 ± 3.0	1.0 ± 6.0
Nobj_5	24.44 ± 0.07	24.45 ± 0.05	0.72 ± 0.09	43.5 ± 0.2	0.7 ± 0.03
obj_6	23.5 ± 0.04	23.47 ± 0.04	–	35.0 ± 3.0	6.0 ± 7.0
obj_7	24.83 ± 0.09	24.78 ± 0.09	–	41.0 ± 3.0	15.0 ± 10.0
Nobj_8	23.74 ± 0.04	23.73 ± 0.04	0.4 ± 0.1	45.0 ± 3.0	1.67 ± 0.01
obj_9	24.33 ± 0.07	24.29 ± 0.07	–	35.0 ± 2.0	2.0 ± 6.0
Nobj_10	23.02 ± 0.03	22.98 ± 0.03	0.7 ± 0.1	42.0 ± 3.0	6.0 ± 2.0
Nobj_11	24.19 ± 0.05	24.15 ± 0.05	0.6 ± 0.1	39.6 ± 0.4	7.3 ± 0.6
Nobj_12	23.55 ± 0.04	23.55 ± 0.04	0.53 ± 0.08	41.0 ± 3.0	30.0 ± 10.0
obj_13	24.63 ± 0.08	24.55 ± 0.07	–	40.0 ± 3.0	5.0 ± 8.0
obj_14	24.1 ± 0.05	24.07 ± 0.05	–	32.0 ± 2.0	3.0 ± 5.0
obj_15	24.9 ± 0.09	24.88 ± 0.09	–	30.0 ± 3.0	30.0 ± 20.0
obj_16	25.0 ± 0.1	24.96 ± 0.1	–	43.0 ± 3.0	1.0 ± 8.0
Nobj_17	21.65 ± 0.02	21.63 ± 0.02	0.6 ± 0.09	38.5 ± 0.1	9.6 ± 0.2
Nobj_18	24.43 ± 0.06	24.25 ± 0.06	0.9 ± 0.1	45.0 ± 2.0	0.97 ± 0.01
obj_19	24.88 ± 0.09	24.86 ± 0.09	–	36.0 ± 3.0	9.0 ± 7.0
Nobj_20	24.01 ± 0.05	24.0 ± 0.05	0.45 ± 0.09	44.0 ± 3.0	0.7 ± 0.2
Nobj_21	23.82 ± 0.04	23.79 ± 0.04	0.4 ± 0.09	39.0 ± 5.0	40.0 ± 30.0
obj_22	24.65 ± 0.08	24.62 ± 0.08	–	46.0 ± 3.0	10.0 ± 10.0
Nobj_23	23.96 ± 0.05	23.96 ± 0.05	0.5 ± 0.1	37.0 ± 2.0	1.7 ± 0.6
obj_24	24.75 ± 0.08	24.7 ± 0.08	–	42.0 ± 3.0	3.0 ± 8.0
obj_25	24.86 ± 0.09	24.82 ± 0.09	–	43.0 ± 3.0	3.0 ± 8.0
obj_26	25.0 ± 0.1	25.0 ± 0.1	–	43.0 ± 3.0	2.0 ± 8.0
Nobj_27	24.33 ± 0.06	24.38 ± 0.05	0.33 ± 0.07	38.0 ± 3.0	23.0 ± 9.0
2004 VT75 ^c	21.92 ± 0.03	21.9 ± 0.03	–	37.55	12.823
obj_29	23.65 ± 0.04	23.62 ± 0.04	–	30.0 ± 3.0	19.0 ± 9.0
Nobj_30	24.36 ± 0.06	24.29 ± 0.06	0.6 ± 0.1	46.0 ± 3.0	2.2 ± 0.8
Nobj_31	23.86 ± 0.04	23.78 ± 0.04	0.69 ± 0.09	43.0 ± 2.0	4.0 ± 1.0
Nobj_32	22.07 ± 0.02	22.08 ± 0.02	0.36 ± 0.09	39.39 ± 0.01	9.45 ± 0.01
Nobj_33	23.83 ± 0.04	23.79 ± 0.04	0.7 ± 0.1	38.0 ± 2.0	5.0 ± 2.0
Nobj_34	23.53 ± 0.05	23.54 ± 0.04	0.6 ± 0.1	37.0 ± 2.0	10.0 ± 4.0
Nobj_35	22.9 ± 0.03	22.88 ± 0.03	0.47 ± 0.08	36.2 ± 0.1	20.9 ± 0.4
obj_36	21.57 ± 0.02	21.55 ± 0.02	–	36.0 ± 3.0	14.0 ± 8.0
obj_37	22.51 ± 0.02	22.49 ± 0.03	–	32.0 ± 3.0	20.0 ± 10.0
obj_38	24.52 ± 0.07	24.49 ± 0.07	–	32.0 ± 2.0	11.0 ± 7.0
Nobj_39	23.9 ± 0.05	23.91 ± 0.04	0.58 ± 0.09	43.0 ± 3.0	2.9 ± 0.9
Nobj_40	23.25 ± 0.03	23.21 ± 0.03	0.66 ± 0.09	41.0 ± 2.0	2.6 ± 0.9
Nobj_41	23.77 ± 0.05	23.74 ± 0.05	0.66 ± 0.09	43.0 ± 3.0	2.6 ± 1.0
obj_42	24.26 ± 0.06	24.23 ± 0.06	–	32.0 ± 3.0	30.0 ± 10.0
obj_43	24.74 ± 0.08	24.72 ± 0.08	–	46.0 ± 3.0	8.0 ± 10.0
Nobj_44	24.18 ± 0.05	24.15 ± 0.05	0.38 ± 0.09	46.0 ± 3.0	2.8 ± 1.0
obj_45	24.55 ± 0.07	24.42 ± 0.07	–	47.0 ± 3.0	1.0 ± 10.0
Nobj_46	23.83 ± 0.04	23.8 ± 0.04	0.5 ± 0.1	37.0 ± 3.0	18.0 ± 7.0
Nobj_47	24.31 ± 0.06	24.27 ± 0.05	0.57 ± 0.09	43.0 ± 0.2	0.871 ± 0.002
obj_48	25.3 ± 0.2	25.1 ± 0.1	–	19.0 ± 4.0	40.0 ± 30.0
Nobj_49	23.85 ± 0.04	23.78 ± 0.04	0.56 ± 0.09	44.0 ± 3.0	7.0 ± 2.0
Nobj_50	23.57 ± 0.04	23.53 ± 0.04	0.65 ± 0.09	45.0 ± 2.0	4.0 ± 1.0
obj_51	25.0 ± 0.1	24.95 ± 0.1	–	34.0 ± 2.0	5.0 ± 6.0
obj_52	24.47 ± 0.07	24.41 ± 0.07	–	35.0 ± 3.0	4.0 ± 6.0
Nobj_53	23.92 ± 0.06	23.81 ± 0.06	0.7 ± 0.1	46.0 ± 3.0	2.2 ± 0.6
obj_54	24.95 ± 0.1	24.78 ± 0.09	–	43.0 ± 3.0	3.0 ± 8.0
obj_55	24.98 ± 0.1	24.93 ± 0.1	–	42.0 ± 3.0	2.0 ± 8.0
Nobj_56	24.35 ± 0.06	24.27 ± 0.06	0.6 ± 0.1	47.0 ± 3.0	3.0 ± 1.0
obj_57	24.84 ± 0.09	24.81 ± 0.09	–	43.0 ± 3.0	20.0 ± 10.0
obj_58	25.1 ± 0.1	24.9 ± 0.1	–	24.0 ± 3.0	30.0 ± 10.0
Nobj_59	24.44 ± 0.07	24.22 ± 0.05	0.66 ± 0.07	41.0 ± 0.1	2.14 ± 0.05
obj_60	24.05 ± 0.05	24.01 ± 0.05	–	28.0 ± 2.0	6.0 ± 5.0
Nobj_61	23.64 ± 0.05	23.57 ± 0.05	0.65 ± 0.09	42.0 ± 2.0	2.9 ± 0.9
Nobj_62	24.16 ± 0.07	24.21 ± 0.06	0.44 ± 0.09	43.0 ± 3.0	13.0 ± 5.0
obj_63	23.68 ± 0.04	23.65 ± 0.04	–	22.0 ± 2.0	14.0 ± 7.0
obj_64	24.54 ± 0.07	24.52 ± 0.07	–	42.0 ± 3.0	2.0 ± 7.0
Nobj_65	23.3 ± 0.03	23.27 ± 0.03	0.6 ± 0.1	43.5 ± 0.1	0.82 ± 0.01
obj_66	24.29 ± 0.06	24.26 ± 0.06	–	20.0 ± 8.0	70.0 ± 80.0
Nobj_67	24.44 ± 0.06	24.36 ± 0.06	0.67 ± 0.09	45.0 ± 3.0	1.6 ± 0.3
Nobj_68	23.81 ± 0.04	23.74 ± 0.04	0.64 ± 0.09	41.0 ± 3.0	3.0 ± 1.0
obj_69	24.65 ± 0.08	24.57 ± 0.08	–	42.0 ± 3.0	3.0 ± 8.0
obj_70	24.53 ± 0.07	24.5 ± 0.07	–	41.0 ± 3.0	4.0 ± 8.0
obj_71	23.85 ± 0.04	23.82 ± 0.05	–	34.0 ± 2.0	3.0 ± 5.0
Nobj_72	23.91 ± 0.05	23.88 ± 0.05	0.6 ± 0.1	44.0 ± 2.0	1.4 ± 0.3
Nobj_73	23.94 ± 0.05	23.83 ± 0.05	0.6 ± 0.1	44.0 ± 2.0	2.1 ± 0.8

Table 2 (continued)

Object ^a	r'_{Subaru}	r'_{SDSS}	$(g'_{\text{SDSS}} - r'_{\text{SDSS}})$	R^b (AU)	i^b (deg.)
Nobj_74	24.41 ± 0.08	24.68 ± 0.06	0.35 ± 0.08	41.0 ± 2.0	4.0 ± 1.0
obj_75	25.2 ± 0.1	25.1 ± 0.1	–	36.0 ± 3.0	1.0 ± 5.0
obj_76	24.68 ± 0.08	24.6 ± 0.08	–	42.0 ± 3.0	2.0 ± 8.0
Nobj_77	22.74 ± 0.03	22.72 ± 0.03	0.6 ± 0.1	42.3 ± 0.1	1.24 ± 0.02
Nobj_78	23.74 ± 0.04	23.71 ± 0.04	0.67 ± 0.09	42.0 ± 3.0	2.1 ± 0.3
obj_79	24.85 ± 0.09	24.78 ± 0.09	–	50.0 ± 3.0	1.0 ± 6.0
obj_80	24.58 ± 0.07	24.54 ± 0.07	–	42.0 ± 3.0	5.0 ± 8.0
obj_81	24.03 ± 0.05	24.01 ± 0.05	–	33.0 ± 2.0	6.0 ± 6.0
Nobj_82	24.19 ± 0.05	24.13 ± 0.05	0.78 ± 0.09	43.1 ± 0.1	0.31 ± 0.01
obj_83	23.06 ± 0.03	22.95 ± 0.03	–	35.0 ± 3.0	30.0 ± 10.0
obj_84	24.98 ± 0.1	24.94 ± 0.1	–	41.0 ± 3.0	2.0 ± 8.0
obj_85	24.54 ± 0.07	24.52 ± 0.07	–	30.0 ± 3.0	17.0 ± 9.0
Nobj_86	23.87 ± 0.04	23.84 ± 0.04	0.68 ± 0.09	42.0 ± 3.0	2.1 ± 0.6
obj_87	25.1 ± 0.1	25.1 ± 0.1	–	45.0 ± 3.0	8.0 ± 9.0

^a Objects prefaced with N and D have follow-up observations in November and December, respectively.

^b Barycentric distance and ecliptic inclination determined from *fit_radec* (Bernstein and Khushalani, 2000).

^c Object distance and inclination taken from the Minor Planet Center.

Exposure times were scaled from the flux of each source in the discovery images, and were chosen such that each source would have a photometric signal-to-noise ratio of ~ 10 in each image. Images of the D1 and D4 Supernova fields were taken for calibration purposes.

Due to time constraints, only those objects whose distance might place them beyond 39 AU, and with magnitude in discovery images brightward of $r' = 24.5$ were followed. Forty-one objects satisfied these constraints and were pursued in the follow-up observations.

Due to the geometry of the follow-up observations, asteroid confusion was a concern. The predicted rate of motion of the follow-up targets was used as a diagnostic of whether or not a detected moving object was the correct source. The second CCD of the LRIS detector provided a measure of this asteroid confusion rate, as no Kuiper belt objects were expected to fall within this region of the images. In the November follow-up data, three asteroids with brightnesses and rates of motion consistent with our Kuiper belt targets were found in the second CCD for all follow-up exposures. With the exception of two follow-up pointings, our objects were not confused, as only one moving target per field was identified with a rate of motion consistent with the targeted source. This is consistent with our asteroid confusion rate determined from the other CCD. Special attention for the two objects with confused follow-up was made during the December observations. From the December data, the interloper in the November observations was easily rejected achieving reliable links between the discovery and follow-up images for all follow-up targets. No confusion occurred during the December follow-up.

Our follow-up efforts were rewarded with 100% success rate for all 41 targets satisfying our distance and magnitude cuts. The conditions on the November nights were photometric and of moderate seeing, with full-width at half maximum $\lesssim 1.5''$. On the night in December, while it was photometric, the seeing conditions were mediocre, reducing the observing efficiency compared to the November nights. As such, all of the 41 objects for which we attempted follow-up have month-long arcs, while only a small subset of 10 have arcs longer than this. The results of the follow-up efforts are presented in Table 2.

Astrometric and photometric calibrations of the LRIS images were performed using the same techniques as applied to the Suprime-cam images. The astrometric distortions of the LRIS field were small, but noticeable, and varied with airmass. Distortion maps extracted from the calibration images at airmasses similar to the science images provided residual errors of $\sim 0.3 - 0.4''$ with respect to the USNO-B catalog.

For the LRIS blue-channel, the photometric zeropoint was found to be $Z_{g_{\text{Keck}}} = 27.91 \pm 0.03$ with an airmass term $A_g = 0.15 \pm 0.05$. During the observations, the LRIS red-channel detectors were plagued by electronics difficulties causing charge transfer inefficiencies that were dependent on source flux. This effect was found to be as much as $\sim 10\%$ in engineering images. As such, we adopt a 10% uncertainty on the zeropoint of this detector, and find, $Z_{r_{\text{Keck}}} = 28.55 \pm 0.1$. The red-airmass term was found to be $A_r = 0.08 \pm 0.03$.

The conversions between the LRIS r and g magnitudes and the r' and g' Mega-pipe magnitudes were found to be

$$m(r)_{\text{Keck}} = m(r'_{\text{Mega}}) - 0.2(g'_{\text{Mega}} - r'_{\text{Mega}}) \quad (4)$$

and

$$m(g)_{\text{Keck}} = m(g'_{\text{Mega}}) + 1.2(g'_{\text{Mega}} - r'_{\text{Mega}}) \quad (5)$$

The relatively large correction between g_{Keck} and g'_{Mega} is caused by the LRIS beam-splitter configuration which, in the configuration we utilized, truncated the red side of the g_{Keck} filter while preserving the throughput across the r_{Keck} filter.

2.4. Color conversion

To facilitate the combination of the discovery and follow-up images, all photometry needed to be converted to a single system. The Sloan system (Smith et al., 2002) was chosen. The conversion from Megaprime magnitudes to the Sloan system are

$$r'_{\text{Mega}} = r'_{\text{Sloan}} - 0.024(g'_{\text{Sloan}} - r'_{\text{Sloan}}) \quad (6)$$

and

$$g'_{\text{Mega}} = g'_{\text{Sloan}} - 0.153(g'_{\text{Sloan}} - r'_{\text{Sloan}}). \quad (7)$$

From Eqs. 1, 4, and 5 and the conversions presented above, we find that the conversions from the Subaru and Keck photometry to the Sloan system are

$$r'_{\text{Sloan}} = r_{\text{Keck}} - 0.094(g_{\text{Keck}} - r_{\text{Keck}}) \quad (8)$$

$$g'_{\text{Sloan}} = g_{\text{Keck}} - 0.445(g_{\text{Keck}} - r_{\text{Keck}}) \quad (9)$$

and

$$r'_{\text{Sloan}} = r_{\text{Subaru}} - 0.019(g_{\text{Keck}} - r_{\text{Keck}}) \quad (10)$$

Using Eqs. (8)–(10), all photometry have been converted to the Sloan system. The photometry presented in Table 2 are the weighted averages of all measurements presented here. When no $(g_{\text{Keck}} - r_{\text{Keck}})$

r_{Keck}) color was available, the average color of all those objects that did receive follow-up, $(g_{Keck} - r_{Keck}) = 1.21$ was used to convert to the Sloan survey. As the range of Keck colors for our sample is $0.68 \leq (g_{Keck} - r_{Keck}) \leq 1.96$, we estimate the error in the conversion caused by using this average color is ~ 0.02 magnitudes, negligibly small.

In Fig. 7 we present the $(g'_{Sloan} - r'_{Sloan})$ color versus inclination for those objects with follow-up observations. From this figure, it can be seen that our sample exhibits similar behavior to the Kuiper belt objects in the Minor Planet Center analyzed by Peixinho et al. (2008). That is, there is a correlation with color and inclination; low inclination objects are typically redder than higher inclination objects. As both our colors and inclinations are significantly more inaccurate than those in the sample analyzed by Peixinho et al. (2008), a repeat of the same analysis on our data is not warranted, as no more insight would be gained than by visually comparing our sample to theirs (see Fig. 1 of Peixinho et al. (2008)).

3. Analysis

As found by Bernstein et al. (2004), there seems to be some variation in the Kuiper belt size distribution with orbital excitation. More specifically, they defined two populations, the *Cold* sample, which contains those objects with heliocentric distances, $38 < d < 55$ AU and inclinations, $i < 5^\circ$, and the *Excited* population as all those Kuiper belt objects in the same distance range, but with large inclinations. Bernstein et al. (2004) found that for bright objects ($R < 24$), the *Cold* population had a much steeper size distribution than the *Excited* population. This result was found from a sample of Kuiper belt objects compiled from a large number of different surveys, providing a result possibly affected by calibration errors and sky density variations.

Elliot et al. (2005) analyzed the results of the Deep Ecliptic Survey, and found similar results. That is, that the *Cold* classical objects have a steeper size distribution than the resonant, or excited populations. This result however, was drawn from a survey without a calibrated detection efficiency, making the result untrustworthy.

Fuentes and Holman (2008) performed a similar analysis as Bernstein et al. (2004), but with additional survey data. Their findings were similar, i.e., that the *Hot* population size distribution is

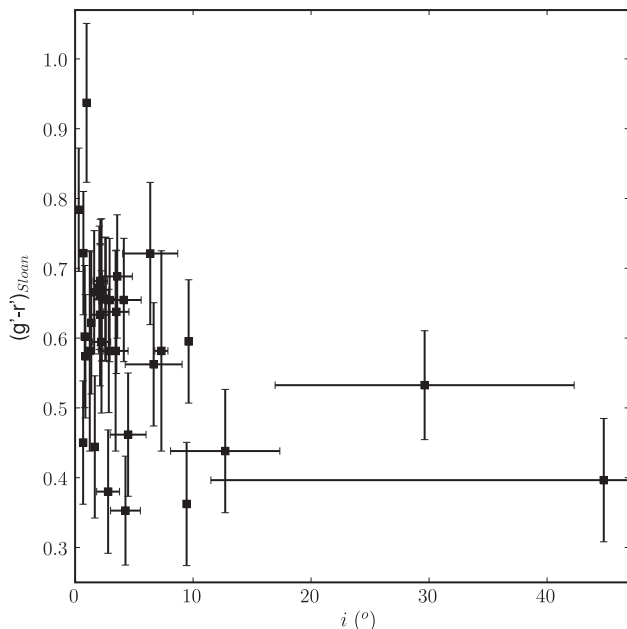


Fig. 7. Sloan color versus inclination for those objects which received follow-up observations.

shallower than that of the *Cold* population. But much like Bernstein et al. (2004), they considered data from multiple surveys and may have been affected by the same calibration errors and sky density variations.

Fraser et al. (2008), Fraser and Kavelaars (2009) reanalyzed the survey data considered in Bernstein et al. (2004) along with new observations, and introduced a technique which accounted for possible errors induced from combining the results of different surveys when measuring the size distribution. They found that the apparent differences between the *Hot* and *Cold* populations could not be disentangled from possible effects caused by the combination of different surveys. When correctly accounting for these effects, no statistical difference between the *Hot* and *Cold* population was found. Population differences as large as those inferred by Bernstein et al. (2004) might exist, but their presence could not be discerned from the available datasets.

The survey we present here, has sufficient depth, and number of detections to probe the differences in size distributions of the *Hot* and *Cold* populations alone, without the need for other data. By doing so, we can ensure that the biases that may be introduced from the use of multiple datasets are avoided here providing a clean and reliable test for any differences between the *Hot* and *Cold* populations of the Kuiper belt.

3.1. The samples

We want to test the findings of Bernstein et al. (2004). To that end, we define subsets of our detections, which are similar to those considered by Bernstein et al. (2004). They are defined as follows:

1. We define *TNO* sample, as all the detections in our sample.
2. Like Bernstein et al. (2004) we define the *Cold* population as those objects with $38 < d < 55$ AU and $i < 5^\circ$. We also further refine this, and define the *Cold_F* sample as only those sources from the *Cold* sample who received follow-up observations in addition to the discovery observations.
3. We define the *Hot_F* and *Hot* samples as those objects with $38 < d < 55$ AU and $i > 5^\circ$, who have and have not received follow-up observations, respectively.
4. We define the *Close* population, as those objects with $30 < d < 38$. We do not make any distinction about follow-up, as the majority of the *Close* population was not observed beyond the discovery observations.

We note here that the exact inclination division between the *Cold* and *Hot* populations is uncertain. Measurements of the inclination distributions of the *Hot* and *Cold* samples suggest that the vast majority of *Cold* classical objects will have inclinations less than $i \sim 5^\circ$ (Brown, 2001; Gulbis et al., 2010). Analysis of the optical color distribution of Kuiper belt objects reveals a correlation of color with inclination (Peixinho et al., 2008 for a recent example, see) that suggests there is a division between low-inclination red objects, and low-inclination neutral objects at $i \sim 12^\circ$. Given the uncertainty of the inclination division that separates the *Cold* and *Hot* populations, we consider the full range of inclination divisions testable by our observations and primarily discuss the historical division of $i = 5^\circ$ unless otherwise stated.

The *Close* population is a mix of objects in mean-motion resonances with Neptune, the Centaurs, and the scattered disk objects. On the other hand, the *Hot* population consists of *Hot* classical, resonant, and scattered disk objects. While the exact fractional mix of each of these populations cannot be determined from our observations, the Minor Planet Center can guide us as to which populations dominate these subsamples. Analysis of the objects in the Minor Planet Center, near opposition in late October, within a few degrees of the ecliptic, reveals 13 objects

satisfying $30 < d < 38$ AU, 6 of which are Plutinos, and 36 objects satisfying $d > 38$ AU and $i > 5^\circ$, of which only a few are Plutinos, with the majority being *Hot* classical and scattered disk objects. As the relative mixes of each dynamical class are different for the *Hot* and *Close* subsamples, any differences detected in the size distributions of the subsamples can provide insight into the size distributions of the underlying populations.

3.2. The methods

As the Kuiper belt objects we detect are not resolved, we have no measure of their sizes, and therefore cannot measure the size distribution of our sample directly. Rather, we must use an indirect technique, and infer the size distribution from the luminosity function. Brightward of $R \sim 25$, the luminosity function is well represented by a power-law. That is, the differential surface density of objects with magnitude m per square-degree is given by

$$\Sigma(m) = \alpha \ln(10) 10^{\alpha(m-m_0)} \quad (11)$$

where α is the logarithmic slope of the power-law, and m_0 is the magnitude at which there is one object per square degree with that magnitude, or brighter. Recent measurements suggest that, for the *TNO* sample, $\alpha = 0.73\text{--}0.76$ and $m_0 \sim 23.4$ in the R-band (Fuentes et al., 2009; Fraser and Kavelaars, 2009). It is worth noting that the luminosity function has a break, or transition from the steep slope for large objects, to a shallower distribution for fainter sources. The transition occurs around $R \sim 25$, which is at the tail end of our survey sensitivity. As such, the break will have little to no effect on our observations, and we ignore it in our analysis.

It can be shown that if the size distribution of a population is a power-law, with slope q , i.e., $\frac{dN}{dr} \propto r^{-q}$, then the luminosity function of that population is given by Eq. (11), with slope $\alpha = \frac{q-1}{5}$. As such, the slopes of the size distributions of each population can be determined from their luminosity functions (see Fraser et al. (2008) for a thorough discussion of this technique).

The fits of Eq. (11) is done with a Bayesian maximum likelihood technique. Specifically, the likelihood

$$L(\{m\}|\alpha, m_0) = e^{-\Omega \int \eta(m) \Sigma(m|\alpha, m_0) dm} \prod_i \sigma(m_i) \Sigma(m_i|\alpha, m_0) \quad (12)$$

is maximized over the luminosity function slope and normalization parameters, α and m_0 . Here Ω is the areal coverage of our survey, $\{m\}$ is the set of magnitudes for our discovered objects, with m_i the magnitude of object i . $\sigma(m_i)$ is a functional representation of the uncertainty in the magnitude m_i . As standard practice, we adopt a gaussian representation, with widths equal to the uncertainty in the observed magnitude of each source.

To avoid potential errors induced at low detection efficiencies, we consider only those sources with probability of detection greater than 50% and truncate our detection efficiency below this point. Fraser et al. (2008) has demonstrated that truncating the efficiency at 50% as we do here causes the best-fit slope α to appear roughly 3–5% steeper than in reality. This effect however, is much smaller than the uncertainty in the best-fit slopes we present. For the *Cold_F* and *Hot_F* samples, our follow-up is limited to those sources with $r'_{\text{Subaru}} < 24.5$. Thus $r' = 24.5$ is our magnitude cut for the *Cold_F* and *Hot_F* samples. In Eq. (11) we utilize only the magnitudes from discovery observations alone, as utilizing the data from other filters could possibly introduce biases into the results. We note however, that when utilizing all available flux measurements, the change in the results was significantly smaller than the uncertainties in the best-fit parameters.

To test the quality of the best-fits, we utilize the Anderson–Darling statistic,

$$\Delta = \int_0^1 \frac{(S(m) - P(m))^2}{P(m)(1 - P(m))} dP(m) \quad (13)$$

where $P(m)$ is the cumulative probability of detecting an object with magnitude $\leq m$, and $S(m)$ is the cumulative distribution of detections. We calculate the probability, $P(\Delta > \Delta_{\text{obs}})$ of finding a value, Δ , larger than that of the observations, Δ_{obs} , given the best fit-parameters by bootstrapping the statistic, i.e., randomly drawing a subsample of objects from the best-fit power-law, with number equal to that detected in a particular sample, fitting Eq. (11) to that random sample, and computing Δ . Values of $P(\Delta > \Delta_{\text{obs}})$ near 0 indicate that the functional form is a poor representation of the data.

3.3. The results

The luminosity functions of the *TNO*, *Cold*, *Hot*, and *Close* samples are presented in Fig. 8. The results of the fits of Eq. (11) to the various subsamples are shown in Fig. 9, and Table 3.

As can be seen from Figs. 8 and 9, the *Cold_F* exhibits a much steeper luminosity function, with slope $\alpha_{\text{Cold}} = 0.82 \pm 0.23$ than the *Hot_F* population which has slope $\alpha_{\text{Hot}} = 0.35 \pm 0.21$. The slopes of these two populations differ at more than the 1- σ level. Both of these samples are well described by power-laws, as exhibited by their Anderson–Darling statistics (see Table 3). Similar slopes within the uncertainties are found from the *Hot* and *Cold* samples. But these values are less trustworthy as the inaccurate inclinations of those objects which did not receive follow-up cause an uncertain amount of mixing between the two subsamples.

In addition, the *Close* sample exhibits virtually the same luminosity function slope, $\alpha_{\text{Close}} = 0.40 \pm 0.15$ as the *Hot_F* (and *Hot*) sample. As the *Close* and *Hot* subsamples are made up of different fractions of the Centaur, resonant, *Hot* classical, and scattered populations, these results suggests that all of these populations exhibit equally shallow luminosity functions. If one or more of the populations had a luminosity function as steep as the *Cold* population, it would likely be detectable as a difference in α between the *Hot* and *Close* populations, the steeper being the subsample with the greatest fraction of the steep dynamical population. This however, is not apparent. Indeed, the slope does not change when considering the *Hot* and *Close* populations together, resulting in $\alpha_{\text{Hot+Close}} = 0.40 \pm 0.12$.

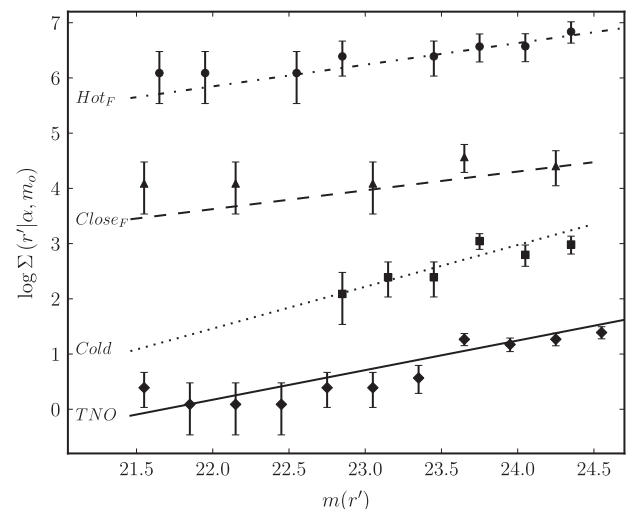


Fig. 8. The differential luminosity functions of the various samples defined in Section 3.1 offset in units of 2 for clarity. Diamonds: *TNO*. Squares: *Cold_F*. Triangles: *Hot_F*. Circles: *Close*. Error-bars are the 1- σ poisson limits for the number of objects in each bin. Lines are the best-fit power-laws, with values given in Table 3.

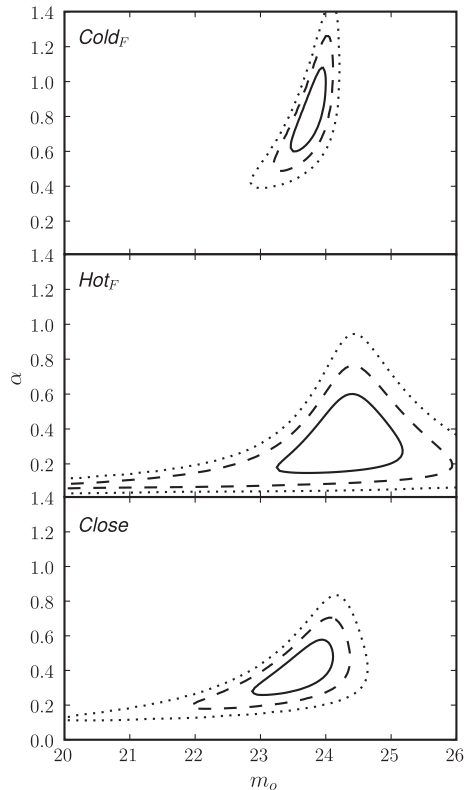


Fig. 9. The 1 (solid), 2 (dashed) and 3- σ (dotted) likelihood contours of the fits presented in Fig. 8 and Table 3. The corresponding subsample is labeled in the top right of each panel.

Table 3
Best-fit power-law parameters.

Sample	α	$m_0(r')$	$P(\mathcal{A} > \mathcal{A}_{obs})$
TNO	0.56 ± 0.1	22.9 ± 0.4	0.64
Cold _F	0.82 ± 0.23	23.8 ± 0.3	0.28
Cold	0.79 ± 0.20	23.8 ± 0.3	0.47
Hot _F	0.35 ± 0.21	24.3 ± 0.7	0.75
Hot	0.35 ± 0.19	24.3 ± 0.7	0.65
Close	0.40 ± 0.15	23.6 ± 0.6	0.68

The slopes of the TNO, Hot, Cold, and Close samples (rows 3, 5, and 6) are likely a few percent steeper than in actuality. This bias however, is much smaller than the uncertainties of those parameters (see Section 3.2).

The luminosity function of TNO sample has a slope $\alpha_{TNO} = 0.56 \pm 0.1$, which is significantly shallower than the slope $\alpha \sim 0.75$ found from other recent measurements in the same magnitude range (Fuentes et al., 2009; Fraser and Kavelaars, 2009). This surprising result can be understood relatively simply. The TNO sample, is a mixture of the Hot, and Cold populations, which our results have shown have significantly different slopes. As such, we expect the TNO sample to have a slope bounded by the slopes of the Hot ($\alpha_{Hot} \sim 0.4$) and Cold ($\alpha_{Cold} \sim 0.8$) populations. Our observations were made at a ecliptic longitude where Plutinos, which are primarily members of the Hot population, are preferentially at perihelion (see above). As such, we expect a greater fraction of Plutinos detected in our observations, than at other longitudes where Plutinos are not at perihelion. As the Hot population has a shallower luminosity function than the Cold population, we expect to see a flatter luminosity function for the TNO sample at this longitude than at others. This simple reasoning can account for the variation in luminosity function slopes seen in past surveys (see Fraser et al., 2008).

Along with the size distribution differences between the Hot and Cold populations, the color distribution (Tegler and Romani-shin, 2000; Trujillo and Brown, 2002; Peixinho et al., 2008 and see Fig. 7), inclination distribution (Brown, 2001), binary fraction (Stephens and Noll, 2006) and lack of large objects on dynamically Cold orbits (Brown, 2008) suggest that these two populations are different. There is no clear evidence however, for a clean separation in inclination between the two. Rather, it is more likely that a smooth gradient exists, and as such, the historical division of $i_{div} = 5^\circ$ chosen to separate these two populations is relatively arbitrary. As such, we measured the luminosity function slopes while varying i_{div} . The results are presented in Fig. 10.

As can be seen, the Cold and Hot population slopes become significantly different for $i_{div} \gtrsim 5^\circ$. When considering all objects, not just those with follow-up, the slope of the Hot population seems to become a constant, with $\alpha_{Hot} \sim 0.4$ for $i_{div} \geq 6^\circ$. This suggests that above 6° the fraction of the population with a steep size distribution is insignificant, and the observed objects come almost entirely from the population with a shallow size distribution. As the uncertainty on α is still quite large, these observations however, are insufficient to confirm such a hypothesis.

To test the significance of the apparent difference in luminosity functions of the Hot and Cold populations, we utilize two different statistical tests. We first utilize the Kuiper-variant of the Kolmogorov–Smirnov test as a non-parametric measure of the significance in the observed difference between two populations (Press, 2002). We randomly bootstrapped from the cumulative luminosity function of the Cold sample, a sample of objects equal in number to the Hot sample. We then calculated the KS-statistic of this random sample compared to the Cold sample. This process was repeated, and from this the probability of finding a simulated KS-statistic as large or larger than that found from the actual Hot population was determined. We found that the two populations were drawn from separate parent populations at the 80–90% significance levels for inclination divisions $i_{div} \geq 4^\circ$.

While the KS-test provides a non-parametric test, a better measure of the significance difference of the Hot and Cold populations

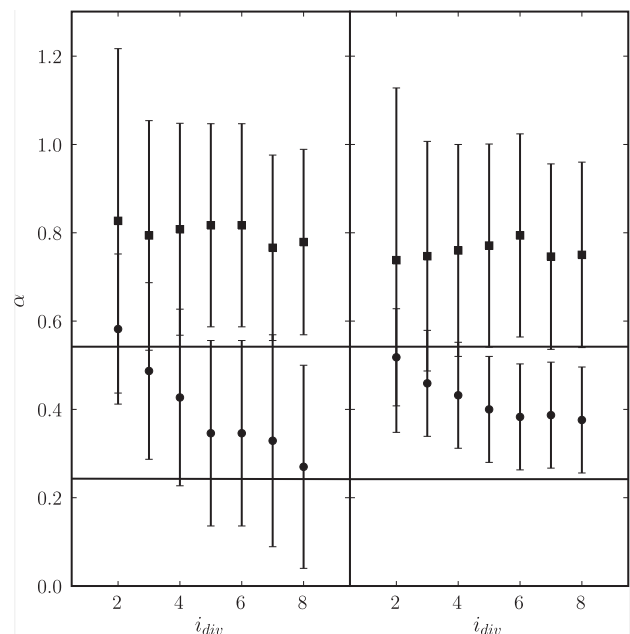


Fig. 10. Best-fit slopes α of the Cold (squares) and Hot (circles) populations versus the inclination division i_{div} separating the two. Left is using only those objects with follow-up. Right is using all observations. The 1- σ range in α_{Close} is bracketed by the two horizontal lines.

can be found with the knowledge that the two populations are well described by power-laws. To that end, we also utilized the Anderson–Darling statistic, as done in Bernstein et al. (2004) and Fraser et al. (2008). Following similar procedures as above, by randomly sampling from the best-fit power-law of the $Cold_F$ sample we determined the probability of finding a simulated Anderson–Darling statistic as large or larger than that found from the actual Hot_F population as compared to the observed $Cold_F$ sample. We found that the two populations were drawn from separate parent populations at greater than the $3-\sigma$ significance for inclination divisions $i_{div} \geq 4^\circ$.

4. Discussion

4.1. Implications for the Kuiper belt

The observed luminosity functions imply differential size distribution slopes $q_{Cold} = 5.1 \pm 1.1$, $q_{Hot} = 2.8 \pm 1.0$, and $q_{Close} = 3.0 \pm 0.8$ for the *Cold*, *Hot*, and *Close* populations. The consistency of the *Hot* and *Close* populations leaves us to consider the two populations together, implying a slope for the combined population of $q_{Hot+Close} = 3.0 \pm 0.6$.

Though the results presented by Bernstein et al. (2004) and Fuentes and Holman (2008) were possibly affected by sky density variations and calibration errors, we find similar conclusions, i.e., the *Cold* population size distribution is steeper than the *Hot* population size distribution. Given the similarity in these repeated measurements of the Kuiper belt luminosity function, the results stand confident.

While over the magnitude range of our observations, both the *Hot* and *Cold* populations are well described by power-law models, other works have put into question whether the power-law behavior extends to all brightnesses. The fact that the luminosity function of the *TNO* population exhibits a roll-over at magnitudes $R \gtrsim 25$ is well accepted. The results of Bernstein et al. (2004) however, suggest that the power-law behavior of the *Cold* population breaks down for the brightest objects. Specifically they find that at the bright-end, the *Cold* population luminosity function has a steeper slope than at fainter magnitudes. Similarly, Morbidelli et al. (2009) suggests that the *Hot* and *Cold* populations are intimate mixtures of two primordial populations, one with a steep size distribution, and one with a shallow size distribution. In such a scenario, both populations should exhibit shallow slopes for the largest objects, then turn-up to a steeper slope for smaller objects, before finally breaking to a shallow slope at some size where collisional processing has dominated. To that end, we test the power-law behavior of both the *Hot* and *Cold* populations.

For the *Cold* population, a simple extrapolation of the best-fit luminosity function suggests that the brightest object on the sky in this population should have a magnitude of $R \sim 19.5$. The entire low-latitude Kuiper belt has been surveyed for objects to a limiting magnitude of $R \lesssim 21$ (Trujillo et al., 2003), and the brightest known *Cold* object has $R \sim 21.3$, nearly a full magnitude fainter. This observation confirms the results of Bernstein et al. (2004). Namely, that the power-law behavior of the *Cold* population luminosity function cannot extend to the brightest targets. Rather the power-law must be truncated. The exact behavior cannot be determined from the observations we present here. The suggestion by Morbidelli et al. (2009) that the *Cold* population size distribution will have a shallow slope for the largest objects, and a turn-up to the observed steep distribution is excluded by this result.

Similarly, extrapolating the best-fit power-law luminosity function of the *Hot* population suggests that this population is well described by a power-law to its brightest objects. Indeed, when excluding the largest objects which are known to have different albedos than the objects observed here (Stansberry et al., 2008)

the absolute magnitude distribution of the biggest objects has a slope compatible with our observations (Brown, 2008; Morbidelli et al. 2008). To test the exactness of a power-law requires combination of other survey data sensitive to the brightest *Hot* members. As well this analysis should include modeling of the latitude distribution of the *Hot* population. The fact however, remains that the *Hot* population has a flat size distribution over all observable sizes.

The behavior of the *Hot* population luminosity function at the faint end is uncertain; the shallow slope of $\alpha_{Hot} \sim 0.35$ for $R \lesssim 25$ is compatible with the lack of faint detections of the *Hot* population in fainter surveys, eliminating the need for a break at the faint end. If however, the *Hot* population slope is as steep as the upper limits of our confidence interval, a break at magnitudes fainter than $R \sim 26$ is still required. The existence of a break in the *Hot* population will only be confirmed by an off-ecliptic survey sensitive to objects with $R > 26$.

The turn-up, as proposed by Morbidelli et al. (2009) would produce an abundance of faint objects in our observed *Hot* population. We can test this utilizing the Anderson–Darling statistic. We generate a fake *Hot* subsample from a shallow power-law with the observed *Hot* population slope that turns up to the best-fit observed slope of the *Cold* population, $\alpha_{Cold} = 0.8$, at some magnitude m_{TU} . We then fit a power-law to that sample, and calculate the Anderson–Darling statistic. This is repeated, and the probability of finding a statistic worse than the observations is calculated versus the value of m_{TU} . The strength of this test is weakened by the sparse sampling of high-latitude sources in our dataset. We still however, eliminate such a turn-up to the slope of the *Cold* population for $m_{TU} < 24.2$ (r') at the $2 - \sigma$ level and < 23.6 at the $3 - \sigma$ level. This is incompatible with the assertion of Morbidelli et al. (2009) who suggest that the *Hot* population should have the same slope as the *Cold* population over an absolute magnitude range of $6.5 < H < 9$, corresponding to r' magnitudes, $22 \lesssim r' \lesssim 24.5$. The significance of the test results over the entire magnitude range however, prevents this result from being iron clad. Clearly, the possibility of a turn-up (or down) must be tested from a survey which detects a large sample of high-latitude objects.

The difference in size distribution slopes of the *Hot* and *Cold* populations suggest very different histories for these two groups. Interestingly, the shallow slope of the *Hot* distribution is compatible with a heavily collisionally processed population, either one that has reached collisional equilibrium, or in which the largest objects are fragments of even larger, disrupted primordial bodies (O'Brien and Greenberg, 2003; Bottke et al., 2010). For collisional evolution to completely reshape the size distribution of the *Hot* population would require extremely high collision rates, seemingly incompatible with plausible protoplanetary disk densities, and formation scenarios (Stern, 1996; Kenyon and Bromley, 2004; Fraser, 2009). Rather it is likely that this slope is the result of the accretionary processes that formed the *Hot* population.

Unlike the *Hot* population, the steep slope of the *Cold* population is entirely incompatible with a collisionally evolved distribution. This slope must be the result of accretionary processes as well.

The shallower slope of the *Hot* population, and the fact that the largest objects of the *Hot* population are larger than those of the *Cold* population, implies that the *Hot* population achieved a more advanced stage of accretion than the *Cold* population (Kenyon, 2002). The incompatibility of their slopes implies that these two populations underwent different accretion scenarios. It is possible, that the *Hot* population underwent a longer duration of accretion than the *Cold* population. To halt accretion for the *Cold* population would require excitation and mass depletion with some yet unseen perturber beyond the outer edge of the Kuiper belt. The past existence of one or more planetary embryos in the Kuiper belt region is a possible source of this excitation, and has been proposed to

explain some of the Kuiper belt dynamical features (Gladman and Chan, 2006; Lykawka and Mukai, 2008).

Another possibility is that the *Hot* population underwent accretion in a more dense region of the protoplanetary nebula. This would result in more rapid accretion than compared to the *Cold* population, allowing the *Hot* population to grow to larger sizes before the process was halted. Under this scenario, the *Hot* and *Cold* populations could then have similar accretion timescales. As currently favoured formation scenarios suggest the *Hot* population was scattered from a region closer to the Sun than their current locations (Malhotra, 1993; Gomes and Feb., 2003; Levison et al., 2008), where the protoplanetary disk might have been more dense, this scenario seems likely.

However the *Hot* and *Cold* populations came about, their incompatible size distributions imply different accretion scenarios. Once accretion was finished, these objects were excited and emplaced onto their current orbits, creating the architecture of the current Kuiper belt. Given the dynamically *Cold* nature of the *Cold* population, it seems plausible that this population formed in situ. Whatever the mechanism(s) ultimately responsible for the belt, our results show that little mixing between the *Hot* and *Cold* populations has occurred.

4.2. Comparison with other populations

There is a striking similarity in the size distributions of the *Cold* population, and the Jupiter Trojans. Both have similarly steep slopes ($q_{Cold} \sim 5.1$ and $q_{JT} \sim 5.5$) and both exhibit breaks to shallower slopes at roughly the same object diameter (Jewitt et al., 2000; Fraser and Kavelaars, 2009). This result argues strongly against the Trojan formation mechanism of the so-called NICE model in which the Trojan populations and the *Hot* and *Cold* Kuiper belt populations are all scattered into their current regions from the same primordial disk population (Morbidelli et al., 2005; Nesvorný and Vokrouhlický, 2009). If this scenario were true, Morbidelli et al. (2009) has shown that over the magnitude range of our observations, the *Hot* population should have the same slope as that observed for large Jupiter Trojans. Using the Anderson–Darling statistic, we tested the probability of the *Hot* sample being drawn from a luminosity function with the slope of the Jupiter Trojan luminosity function, $\alpha_{JT} = 0.9$. We found that the *Hot* sample could not be drawn from the Jupiter Trojan population at greater than the 3- σ significance. As the size distributions of these two populations in the size range considered have not evolved significantly since they were emplaced in their current regions (Davis et al., 2002; Fraser and Kavelaars, 2009), we must conclude that the *Hot* and Jupiter Trojan populations must have different progenitor populations. This result and the lack of mixing between the *Hot* and *Cold* populations is difficult to reconcile with the NICE model. It seems likely the *Hot*, *Cold*, and Trojan populations formed by separate means. If this is true, the similarities between the *Cold* and Trojan populations are quite a coincidence.

Another similarity is seen between the *Hot* population ($q_{Hot} \sim 3$) and the Jupiter family comets, who exhibit a size distribution slope of $q_{JFC} \sim 2.8$ albeit over a smaller size range, $1 \lesssim D \lesssim 10$ km (Tancredi et al., 2006; Weissman et al., 2009). This resemblance is interesting as one likely source of Jupiter family comets are scattered disk objects – members of the *Hot* population – which have fallen into the inner Solar System under gravitational perturbations from the gas-giants, suggesting that the scattered disk size distribution might be a power-law for $D \gtrsim 1$ km. We consider this possibility here.

While the observations we present do not measure the size distribution of the scattered disk directly, the similarity in slopes between the *Hot* and *Close* subsamples implies that the scattered disk cannot have a size distribution significantly different than that of

the *Hot* sample as a whole. Additionally we cannot determine the total number scattered disk objects from our observations. Rather, we turn to other estimates which suggest that, if their size distribution is a power-law with slope of $q \sim 3$, then there are roughly $10^7 - 10^8$ scattered disk objects with $1 \lesssim D \lesssim 10$ km (Trujillo et al., 2000; Parker and Kavelaars, 2010; Schwamb, personal communication).

Simulations by Volk and Malhotra (2008) suggest that if the scattered disk is the sole source of the Jupiter family comets, then there must be at least 10^9 objects in that population to account for the current flux of Jupiter family comets through the inner Solar System, implying that either the scattered disk is not the sole source of the Jupiter family comets, or that the extrapolation of a power-law to $D \sim 1$ km is unreasonable; it must be that the size distribution of scattered disk objects steepens significantly in the $D \sim 10 - 100$ km range. Further observations are required before this feature can be detected.

5. Conclusions

We have performed an ecliptic survey, and have detected 88 Kuiper belt objects with magnitudes $21 < r'_{Sloan} < 25.2$. A subset of these objects have received additional follow-up observations allowing us to accurately determine their inclinations and distances. Using these data, we have measured the size distribution of the *Hot* and *Cold* subsamples, historically defined as those objects with inclinations above and below 5° , respectively. This measurement, which is independent of any previous observations has confirmed that the *Cold* population has a much steeper luminosity function, with slope $\alpha_{Cold} = 0.82 \pm 0.23$, than the *Hot* population, with slope $\alpha_{Hot} = 0.35 \pm 0.21$.

The observed luminosity functions imply different size distributions for the *Hot* and *Cold* populations. The differential size distribution slopes of the two subsamples are $q_{Cold} = 5.1 \pm 1.1$ and $q_{Hot} = 2.8 \pm 1.0$.

In addition, we have found that the *Close* population, which is defined as those objects with heliocentric distance, $d < 38$ have the same luminosity function slope as the *Hot* subsample, demonstrating that these two share a similar size distribution. In addition, our findings suggest that the dynamical populations which make up both the *Hot* and *Close* populations must all have similar size distributions.

The primary consequence of these findings is that the *Cold* population, which consists primarily of *Cold* classical Kuiper belt objects, has a separate, and distinct accretion history from the *Hot* population, requiring either potentially different accretion timescales for the two populations, or formation in different locations of the protoplanetary disk. These observations reveal the similarities in the size distributions between the subsamples of the Kuiper belt and the Jupiter family comets and Trojans, suggesting a connection between the formation and subsequent evolution of the small body populations of the outer Solar System.

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